			01-2023
•		Name:Computer Graphics	
		:30 AM TO 01:00 PM Total Ma	rks:70
Instru			
		Attempt all questions. Make suitable assumptions wherever necessary.	
		Figures to the right indicate full marks.	
	4.	Simple and non-programmable scientific calculators are allowed.	
			MARK
Q.1	(a)	Write the differences between Random Scan display and Raster Scan	03
		display.	
	<b>(b)</b>	Discuss various ways to represent a polygon mesh in brief.	04
	(c)	Draw and explain working of Cathod Ray Tube with diagram.	07
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Q.2	<b>(a)</b>	c -	03
	<b>(b)</b>		04
	(c)		07
		Write pseudo code for Midpoint circle drawing algorithm. OR	
	(c)		07
	(C)	edge table and criteria for adding and removing edge to active edge	07
		table.	
Q.3	<b>(a)</b>	Write a note on 2D shearing.	03
	<b>(b)</b>	Obtain the matrix transformations for Reflection about the line $y = x$ in	04
		2 – dimensions.	
	(c)	Consider the clipping window with Lower Left coordinate (1,2) and	07
		Upper Right coordinate (8,4). Clip a line P(-6,-1) and Q(-1, 4) using	
		Cohen Sutherland line clipping algorithm.	
0.2	(a)	OR Evaluin limitations of Sutharland Hadaaman polyaon aligning	02
Q.3	<b>(a)</b>	Explain limitations of Sutherland – Hodgeman polygon clipping algorithm.	03
	(b)	e de la companya de la	04
	(0)	viewport in 2D viewing system.	<b>UT</b>
	(c)		07
		of the following sequence of operations is commutative:	
		1) Two successive rotations	
		2) Two successive translations	
Q.4	(a)		03
	(b)		04
-	(c)	List and explain the properties of B-spline curves.	07
0.1	$(\mathbf{c})$	OR Write a short note on 3D rotation	03
Q.4	(a)	Write a short note on 3D rotation.	03 04
	(b) (c)	Compare interpolation spline and approximate spline. List and explain the properties of Bazier curves.	04 07
		List and explain the properties of Dazlet curves.	07
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Q.5	<b>(a)</b>	Explain ambient light in brief.	03

- (b) Write a short note on YIQ color model. 04 (c) Prove that the transformation matrix for the 3D rotation about an 07 arbitrary axis can be expressed as the composition of following seven individual transformations :  $R(\theta) = T-1.Rx-1(\alpha).Ry-1(\beta).Rz(\theta).Ry(\beta).Rx(\alpha).T$ OR Q.5 (a) Explain the property of light using electromagnetic spectrum. 03 04
  - (b) Write a short note on RGB color model.
  - (c) Find out the 3D transformation matrix to rotate a given 3D object by an amount 60 about line passing from point(1,1,1) and the direction vector V=2i+2j+2k.

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